

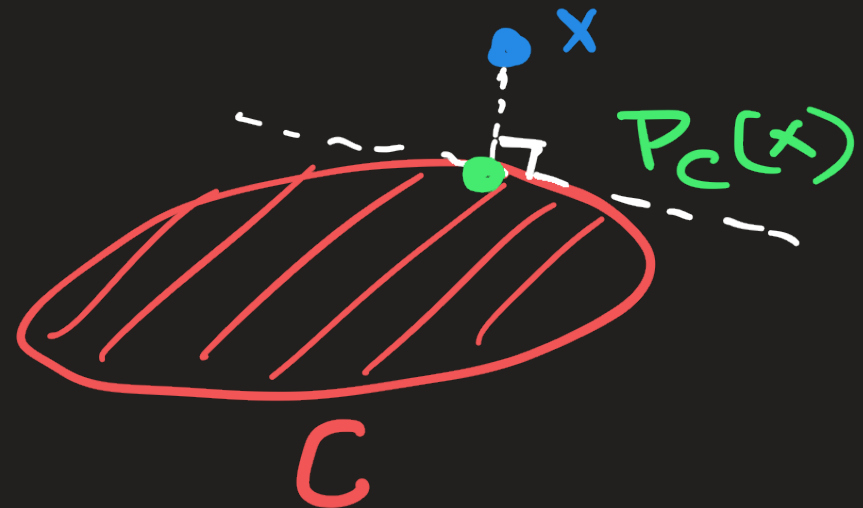
ML & Opt Lecture 8

- Cauchy-Schwarz Inequality
- More examples of convex optim probs
- Optimizing Conditions for Smooth Conv Optim Probs
 - Constrained
 - Unconstrained

Ex

Projection onto convex set

- given a point C , find the closest pt in C to x



$$P_C(x) = \operatorname{argmin}_{z \in C} \|z - x\|_2^2$$

$P_C(x)$ is called the projection of x onto C , and is a well-defined function because the objective $z \mapsto \|z - x\|_2^2$ is strictly convex in z

Fact: if $\nabla^2 f(x) \succ 0$ then f is strictly convex

Consider $f(z) = \|z - x\|_2^2 = \langle z - x, z - x \rangle$
 $= z^T z - 2x^T z + x^T x$

$$\nabla f(z) = 2z - 2x = 2(z - x)$$

$$\nabla^2 f(z) = 2 \cdot I$$

since $x \neq 0 \Rightarrow x^T \nabla^2 f(z) x = \|x\|_2^2 > 0$

we see that $\nabla^2 f(z) \succ 0$, so $f(z)$ is strictly convex.

Note also that $f(z) = \|z\|_2^2 - 2\langle x, z \rangle + \|x\|_2^2$

hence, strictly convex w.r.t. z

strictly convex

convex

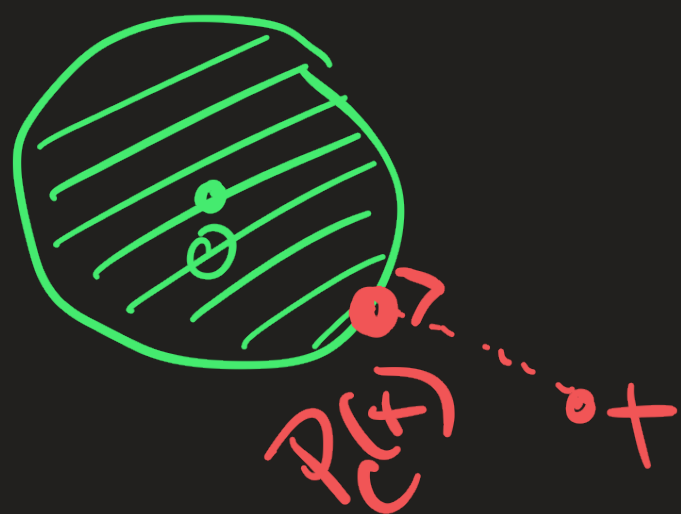
ignorable ∇_x we are minimizing w.r.t. z

We will show later in the lecture that if

$$C = B_{\|\cdot\|_2}(0,1) = \{z \mid \|z\|_2 \leq 1\}$$

then

$$P_C(x) = \begin{cases} x & \text{if } x \in C \\ \frac{x}{\|x\|_2} & \text{if } x \notin C \end{cases}$$



Cauchy-Schwarz inequality

For any two vectors $x, y \in \mathbb{R}^d$,

$$|\langle x, y \rangle| \leq \|x\|_2 \|y\|_2,$$

or equivalently

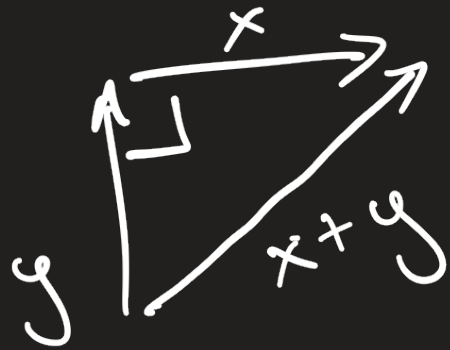
$$\left| \left\langle \frac{x}{\|x\|_2}, \frac{y}{\|y\|_2} \right\rangle \right| \leq 1$$

and $|\langle x, y \rangle| = \|x\|_2 \|y\|_2$ iff $x = \alpha y$ for some $\alpha \in \mathbb{R}$

The CS-ineq allows us to define angles b/w vectors in high-dims, as

$$\cos(\theta \angle x, y) = \left\langle \frac{x}{\|x\|_2}, \frac{y}{\|y\|_2} \right\rangle$$

Intuition



Pythagorean Theorem

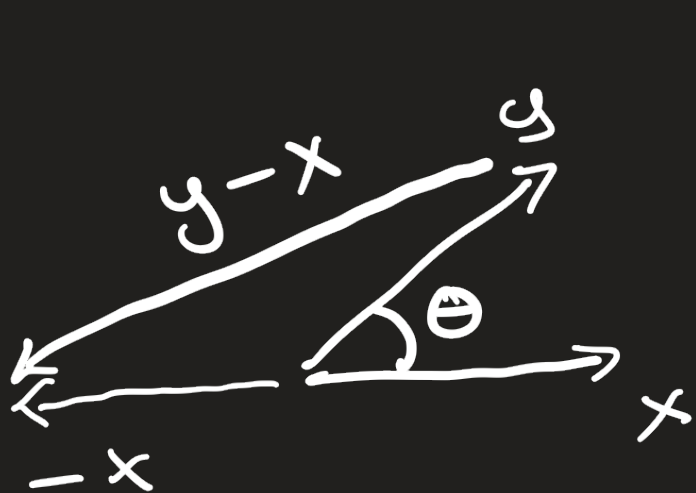
$$\|x+y\|_2^2 = \|x\|_2^2 + \|y\|_2^2 \quad \text{follows from CS:}$$

$$\|x+y\|_2^2 = \langle x+y, x+y \rangle$$

$$= x^T x + 2x^T y + y^T y$$

$$= 0 \quad \text{b/c } \cos \theta(x, y) = 0$$

$$= \|x\|_2^2 + \|y\|_2^2 \quad \Rightarrow \langle x, y \rangle = 0$$



$$\|y-x\|_2^2 = x^T x + y^T y - 2x^T y$$

$$= \|x\|_2^2 + \|y\|_2^2 - 2\|x\|_2\|y\|_2 \cos \theta$$

Law of Cosines

Types of Smooth Convex Optimization Problems

Let f be a differentiable convex func

Unconstrained

(U) $\min_{x \in \mathbb{R}^d} f(x)$ requires $\text{dom}(f) = \mathbb{R}^d$

Constrained

(C) $\min_{x \in C} f(x)$ requires $C \subseteq \text{dom}(f)$

As a caveat, (U) and (C) in general have multiple optimizers, but the minimal value is unique

Optimality Conditions

We want to know when x^* is a solution of (U) or (C), because:

- 1) If it is a simple enough condition, we can directly use them to find x^*
- 2) we can use these conditions to
 - (i) say a priori qualities x^* has, like sparsity
 - (ii) verify the quality of approximate solns
 - (iii) design algorithms for solving (U) & (C)

Optimality Condition for (U)

Fermat's
Condition

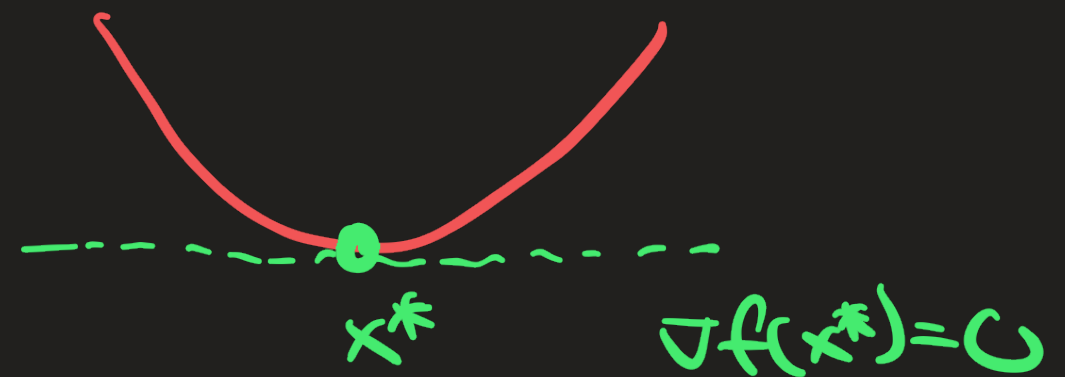
$$x^* \in \operatorname{argmin}_{x \in \mathbb{R}^d} f(x) \quad \text{iff} \quad \nabla f(x^*) = 0$$

Prf

$\Leftarrow$ Assume $\nabla f(x^*) = 0$. Because f is

convex

$$\forall y: \quad f(y) \geq f(x^*) + \nabla f(x^*)^T (y - x^*) \\ = f(x^*)$$



$\Rightarrow$ let x^* be a minimizer.

Now assume that $\nabla f(x^*) \neq 0$. Then
take $y = x^* - \varepsilon \frac{\nabla f(x^*)}{\|\nabla f(x^*)\|_2}$ for an $\varepsilon \in (0, 1)$.

Then we know that

$$f(y) = f(x^*) + \langle \nabla f(x^*), y - x^* \rangle + O(\|y - x^*\|_2^2)$$

$$= f(x^*) + \langle \nabla f(x^*), -\varepsilon \frac{\nabla f(x^*)}{\|\nabla f(x^*)\|_2} \rangle$$

$$+ O\left(\varepsilon^2 \left\| \frac{\nabla f(x^*)}{\|\nabla f(x^*)\|_2} \right\|_2^2\right)$$

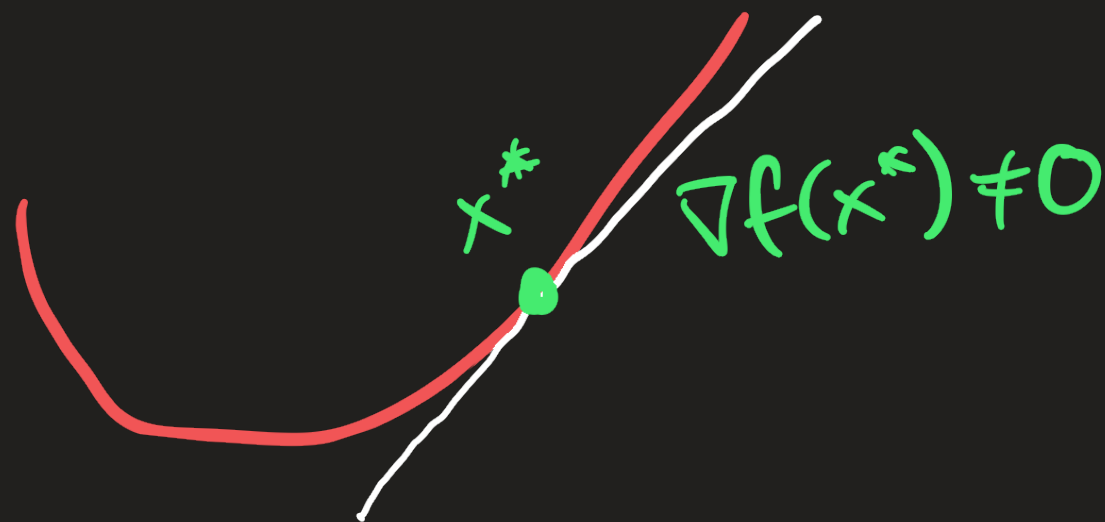
$$= f(x^*) - \varepsilon \|\nabla f(x^*)\|_2 + O(\varepsilon^2)$$

So if $\varepsilon \ll \|\nabla f(x^*)\|_2$ then $\varepsilon^2 \ll \varepsilon \|\nabla f(x^*)\|_2$

$$\begin{aligned} \text{so } f(y) &= f(x^*) - \varepsilon \|\nabla f(x^*)\|_2 + O(\varepsilon^2) \\ &< f(x^*). \end{aligned}$$

This a contradiction, b/c we assumed x^* is a minimizer. Therefore it must be the case that

$$\nabla f(x^*) = 0$$



Consequences

Solving the ^{convex} optimization problem

$$\min_{x \in \mathbb{R}^d} f(x)$$

is as hard/easy as solving the set of equations

$$\nabla f(x) = 0$$

Ex Linear regression

$$\beta^* = \operatorname{argmin}_{\beta} \|X\beta - y\|_2^2 \Leftrightarrow \nabla_{\beta} \|X\beta^* - y\|_2^2 = 0$$

$$\Leftrightarrow 2X^T(X\beta^* - y) = 0$$

$$\Leftrightarrow X^T X \beta^* = X^T y$$

$$\Leftrightarrow \beta^* = (X^T X)^{-1} X^T y$$

Ex

$$x^* = \arg \min_x \|x\|_2^2 + \log \text{sumexp}(x)$$



$$\nabla_x (\|x^*\|_2^2 + \log \text{sumexp}(x^*)) = 0$$

$$2x^* + \text{softmax}(x^*) = 0$$

Observations:

- 1) $-2x^*$ is a probability vector
- 2) objective is strictly convex so x^* is unique, and permutation invariant so any permutation of entries of x^* is a minimizer $\Rightarrow x^*$ is a constant vector

$$x^* = c \cdot \mathbf{1}$$

Because $x^* = c \cdot 1$ and

$$\text{softmax}(x^*) = -2x^*,$$

"

$$\frac{1}{d} = -2c \cdot 1$$

$$\Rightarrow c = -\frac{1}{2d}$$

$$\Rightarrow x^* = \begin{bmatrix} -1/2d \\ \vdots \\ -1/2d \end{bmatrix}$$

Optimality Conditions for (C)



First, note that $\nabla f(x^*) = 0$ is not an optimality condition for (C) in general, e.g.

$$\operatorname{argmin}_{x \in [1, 2]} x^2 = 1, \text{ but } \nabla_x x^2 \Big|_{x=1} = 2 \neq 0$$

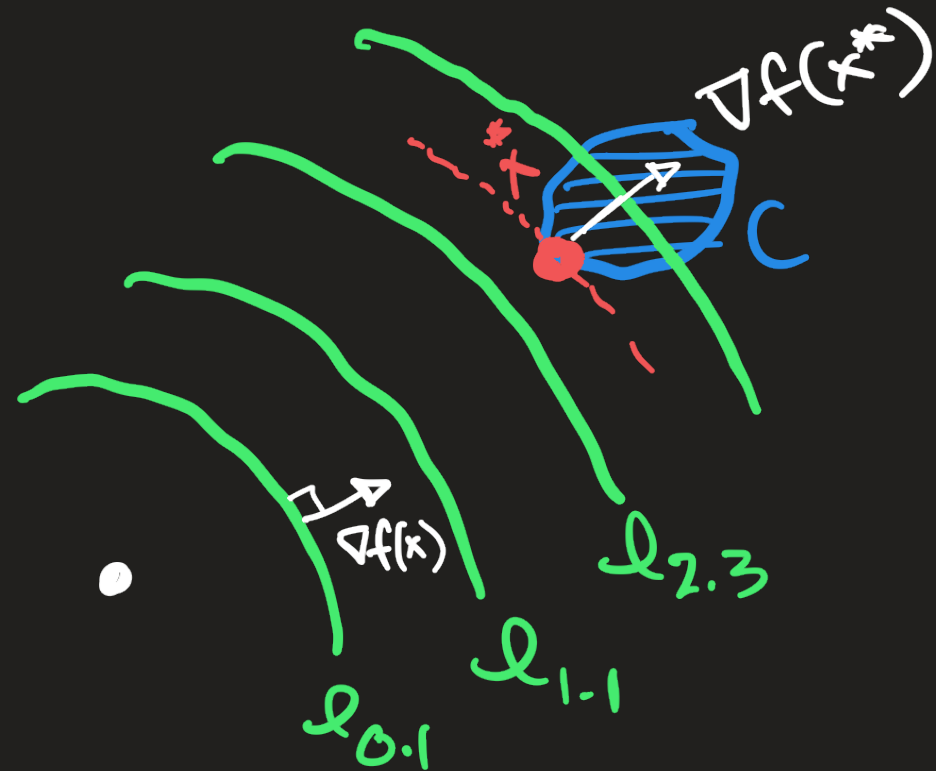
However

$$\operatorname{argmin}_{[-1, 1]} x^2 = 0 \text{ and } \nabla_x x^2 \Big|_{x=0} = 0$$

so we see that the optimality conditions depend on the interaction of f with C

Geometric Interpretation

Consider $\min_{x \in C} f(x)$



Consider the α level sets of f
$$l_\alpha = \{x \mid f(x) = \alpha\}$$

The minimizer x_* must be on the level set of lowest value that intersects C

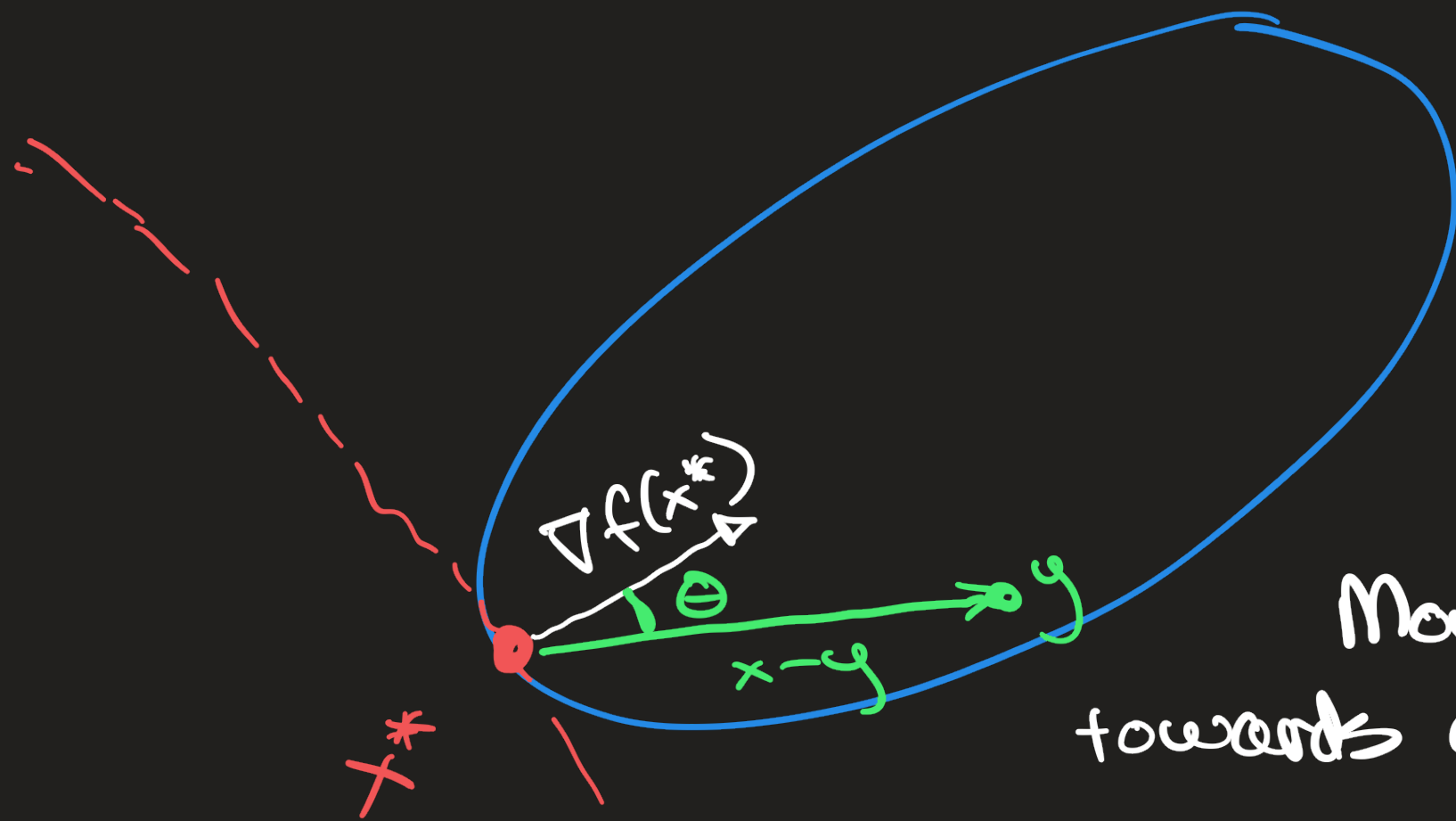
Notice that $\nabla f(x) \perp l_{f(x)}$ at any point x

Imagine that there exists a $y \in C$ such that
 $\langle \nabla f(x^*), y - x^* \rangle < 0$, then

$$\begin{aligned} f(y) &= f(x^*) + \langle \nabla f(x^*), y - x^* \rangle \\ &\quad + o(\|y - x^*\|_2^2) \\ &= f(x^*) + (\text{something negative}) \\ &\quad + o((\text{something negative})^2) \\ &< f(x^*) \end{aligned}$$

so it must be the case that

$$\langle \nabla f(x^*), y - x^* \rangle \geq 0 \quad \forall y \in C$$



Moving from x^*
towards any $y \in C$
must increase f , if
 x^* is a minimizer, i.e.

$$\forall y \in C: \langle \nabla f(x^*), y - x^* \rangle \geq 0$$

Optimality Condition for (C) Fermat's Condition

x^* is a minimizer of

$$\min_{x \in C} f(x)$$

iff for all $y \in C$, $\langle \nabla f(x^*), y - x^* \rangle \geq 0$