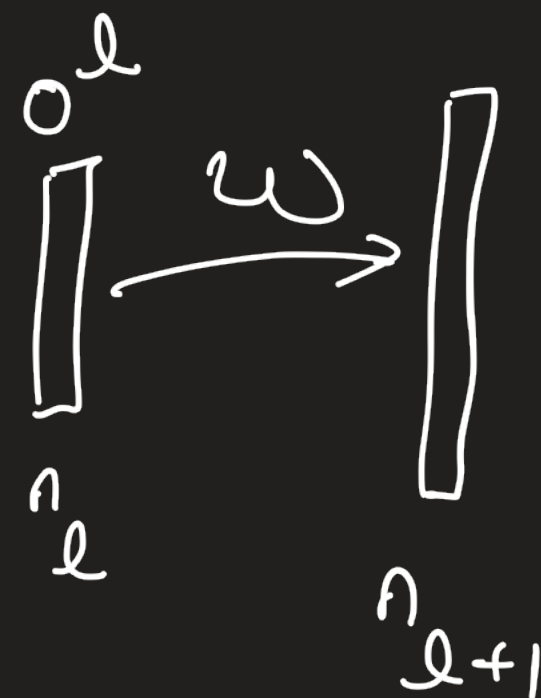


Backpropagation

Determining $\nabla_{\mathbf{o}^l} f \in \mathbb{R}^{n_l}$



$$[\nabla_{\mathbf{o}^l} f]_i = \frac{\partial f}{\partial o_i^l} = \sum_{j=1}^{n_{l+1}} \frac{\partial f}{\partial o_j^{l+1}} \underbrace{\frac{\partial o_j^{l+1}}{\partial o_i^l}}$$

recall $\mathbf{o}^{l+1} = \sigma(\mathbf{a}^{l+1}) = \sigma(\mathbf{w}^{l+1} \mathbf{o}^l + \mathbf{b}^{l+1})$

where $\mathbf{w}^{l+1} = \begin{bmatrix} w_1^{l+1} \\ \vdots \\ w_{n_{l+1}}^{l+1} \end{bmatrix} \in \mathbb{R}^{n_{l+1} \times n_l}$

so
$$o_j^{l+1} = \sigma(\langle \mathbf{w}_j^{l+1}, \mathbf{o}^l \rangle + b_j^{l+1})$$

$$= \sigma\left(\sum_{k=1}^{n_l} \underline{w_{jk}^{l+1} o_k^l} + b_j^{l+1}\right)$$

$$\sum_{k \neq i}^{n_l} w_{jk}^{l+1} o_k^l + b_j^{l+1} + \boxed{w_{ji}^{l+1} o_i^l}$$

$$\frac{\partial o_j^{l+1}}{\partial o_i^l} = \sigma'(a_j^{l+1}) \underbrace{\frac{\partial a_j^{l+1}}{\partial o_i^l}}_{\omega_{ji}^{l+1}} = \underline{(\omega^{l+1})_{ij}^T} \sigma'(a_j^{l+1})$$

$$[\nabla_{o^l} f]_i = \sum_{j=1}^{n_{l+1}} \frac{\partial f}{\partial o_j^{l+1}} \frac{\partial o_j^{l+1}}{\partial o_i^l}$$

$$= \sum_{j=1}^{n_{l+1}} \frac{\partial f}{\partial o_j^{l+1}} \left[(\omega^{l+1})_{ij}^T \sigma'(a_j^{l+1}) \right]$$

$$= \sum_{j=1}^{n_{l+1}} (\omega^{l+1})_{ij}^T \left[\underline{\frac{\partial f}{\partial o_j^{l+1}}} \cdot \sigma'(a_j^{l+1}) \right]$$

$$[\nabla_{o^{l+1}} f]_j \cdot \sigma'(a_j^{l+1})_j$$

$$= \left[(\omega^{l+1})^T \nabla_{o^{l+1}} f \odot \sigma'(a^{l+1}) \right]_i$$

$\Rightarrow$

(1) $\nabla_{o^l} f = \underbrace{(\omega^{l+1})^T}_{\in \mathbb{R}^{n_l \times n_{l+1}}} \underbrace{\left[\nabla_{o^{l+1}} f \odot \sigma'(a^{l+1}) \right]}_{\in \mathbb{R}^{n_{l+1}}}$

$\nearrow$ this is in $\mathbb{R}^{n_l}$

Remember if $x \in \mathbb{R}^d$ & $y \in \mathbb{R}^d$ then
 $x \odot y \in \mathbb{R}^d$ is called the Hadamard / entrywise /
Schur product and satisfies

$$(x \odot y)_i = x_i y_i \quad \text{for } i=1, \dots, d$$

Recall $\frac{\partial f}{\partial \omega^l} = \frac{\partial f}{\partial o^l} \frac{\partial o^l}{\partial \omega^l}$

We will drop the superscript l for convenience since we will be working with quantities on layer l

$$\left[\nabla_{\omega} f \right]_{ij} = \frac{\partial f}{\partial \omega_{ij}} = \sum_{s=1}^n \frac{\partial f}{\partial o_s} \frac{\partial o_s}{\partial \omega_{ij}}$$

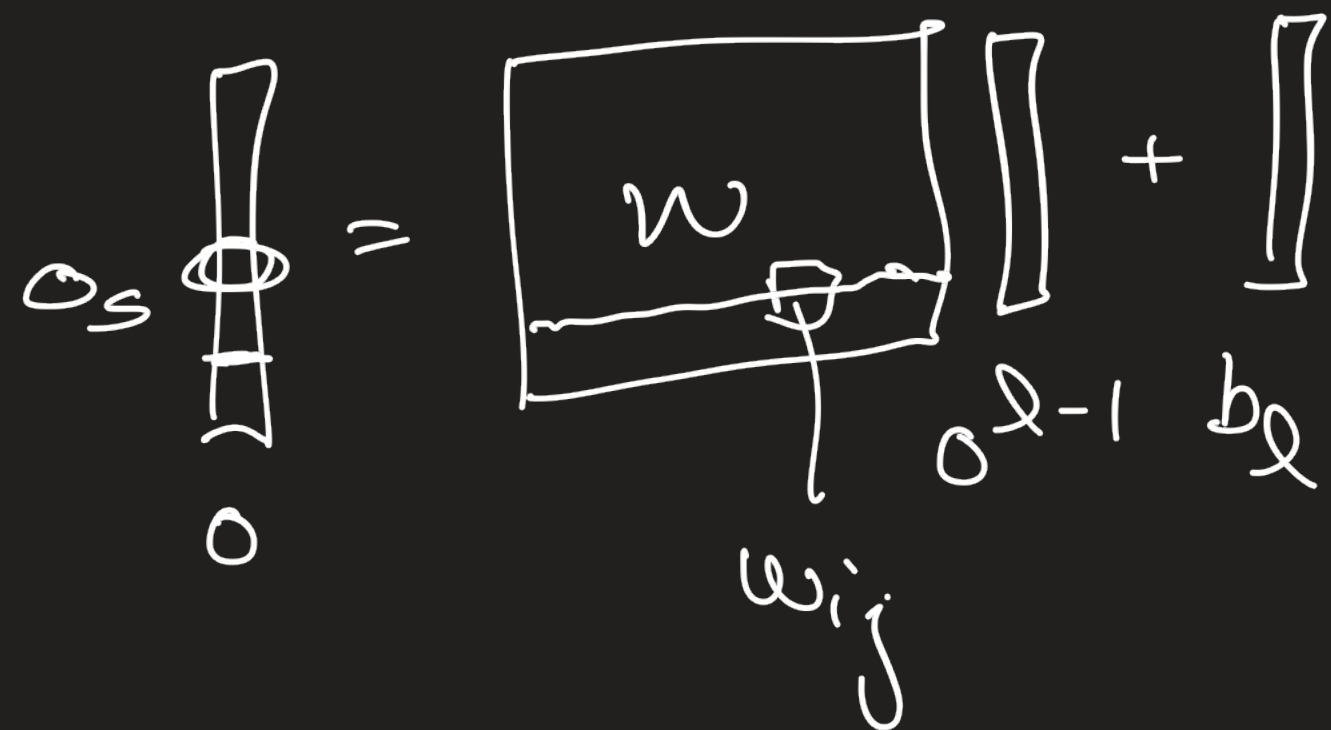
recall $o = \sigma(a) = \sigma(\omega o^{l-1} + b)$

where

$$\omega = \begin{bmatrix} \omega_1 \\ \vdots \\ \omega_n \end{bmatrix}$$

so $o_s = \sigma(a_s) = \sigma(\langle \omega_s, o^{l-1} \rangle + b_s)$

$$\sum_{j=1}^{n_{l-1}} \omega_{sj} o_j^{l-1} + b_s$$



$$\frac{\partial o_s}{\partial w_{ij}} = \begin{cases} 0 & i \neq s \\ \sigma'(a_i) \frac{\partial a_i}{\partial w_{ij}} & i = s \end{cases}$$

recall $a_i = \langle w_i, o^{l-1} \rangle + b_i$

$$= \sum_{j=1}^{n_{l-1}} w_{ij} o_j^{l-1} + b_i$$

$$\Rightarrow \frac{\partial a_i}{\partial w_{ij}} = o_j^{l-1}$$

$$[\nabla_{\omega} f]_{ij} = \sum_{s=1}^n \frac{\partial f}{\partial o_s} \frac{\partial o_s}{\partial w_{ij}}$$

0 unless $i=s$

$$= \frac{\partial f}{\partial o_i} \frac{\partial o_i}{\partial w_{ij}} = \frac{\partial f}{\partial o_i} \sigma'(a_i) o_j^{l-1}$$

$$= \sigma'(a_i) [\nabla_o f]_i (o^{l-1})_j$$

$$= \underline{\sigma'(a_i) [\nabla_o f (o^{l-1})^T]}_{ij}$$

add back the l superscripts

$$(2) \quad \nabla_w f = \underbrace{\text{diag}(\sigma'(a^l))}_{n_l \times n_l} \underbrace{\nabla_{o^l} f \cdot (C^{l-1})^T}_{\substack{n_l \times n_{l-1} \\ \text{matrix}}}^{\boxed{\boxed{\quad}}}$$

$n_l \times n_{l-1}$ matrix as necessary

similarly

$$(3) \quad \nabla_{b^l} f = \underbrace{\nabla_{o^l} f \odot \sigma'(a^l)}_{\substack{n_l \text{ dim vector as necessary}}}$$

n_l dim vector as necessary

This gives the backprop algorithm for computing the required gradient

Backprop Alg (assuming $R=0$)

Inputs: $a^1, \dots, a^L, o^0, \dots, o^L, w_1, \dots, w_L, b_1, \dots, b_L$
assume computed in a forward pass

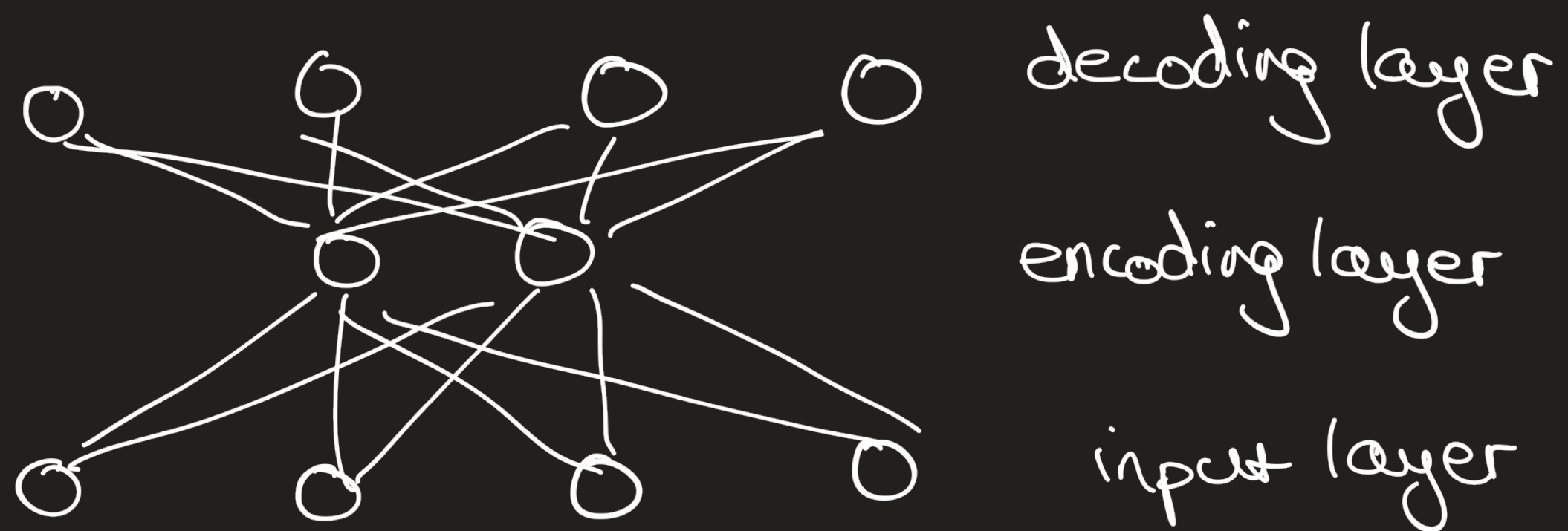
Outputs: $\{\nabla_{w^l} f\}, \{\nabla_{b^l} f\}$ for $l=1, \dots, L$

- Compute $\text{temp} \nabla \leftarrow \nabla_{o^L} f$
- Compute $\nabla_{w^L} f$ and $\nabla_{b^L} f$ using eqns (2) & (3) and $\text{temp} \nabla$

Autoencoders

- Generalizations of PCA & SVD (nonlinear!)

Typically these are used to create useful machine learning features in an unsupervised way



Goal: learn a (compressed, usually) representation that does a good job of reconstructing the input

Ex ℓ_2 -loss $\ell(u, v) = \|u - v\|_2^2$

and $\sigma(x) = x$

$$\begin{aligned}\hat{y}(x) &= o_2 = \sigma(\omega^2 o' + b^2) \\ &= \sigma(\omega^2 \sigma(\omega' o^0 + b') + b^2) \\ &= \sigma(\omega^2 \sigma(\omega' x + b') + b^2) \\ &= \omega^2 \omega' x + \omega^2 b' + b^2\end{aligned}$$

fix $b_1 = b_2 = 0$

$= \omega^2 \omega' x$ where

$$\begin{matrix} & n_1 \\ d & \boxed{} \\ & \omega^2 \end{matrix}$$

$$\begin{matrix} & d \\ n_1 & \boxed{} \\ & \omega_1 \end{matrix}$$

so the ERM is

$$f(\omega_1, \omega_2) = \frac{1}{n} \sum_{i=1}^n \|\hat{y}(x_i) - x_i\|_2^2$$

$$= \frac{1}{n} \sum_{i=1}^n \|\omega_2 \omega_1 x_i - x_i\|_2^2$$

$$= \frac{1}{n} \|\omega_2 \omega_1 X - X\|_F^2$$

where $X = [x_1 | \dots | x_n]$

so fitting this autoencoder learns matrices ω_1, ω_2
 $\in \mathbb{R}^{d \times n_1}, \mathbb{R}^{n_1 \times d}$ to minimize

$$\|\omega_2 \omega_1 X - X\|_F^2, \text{ this is the } \underline{\text{SVD}}$$

Deep autoencoders:

